

# Analysis of impact of spatial heterogeneity in retrieval of geophysical parameters from low-frequency radars

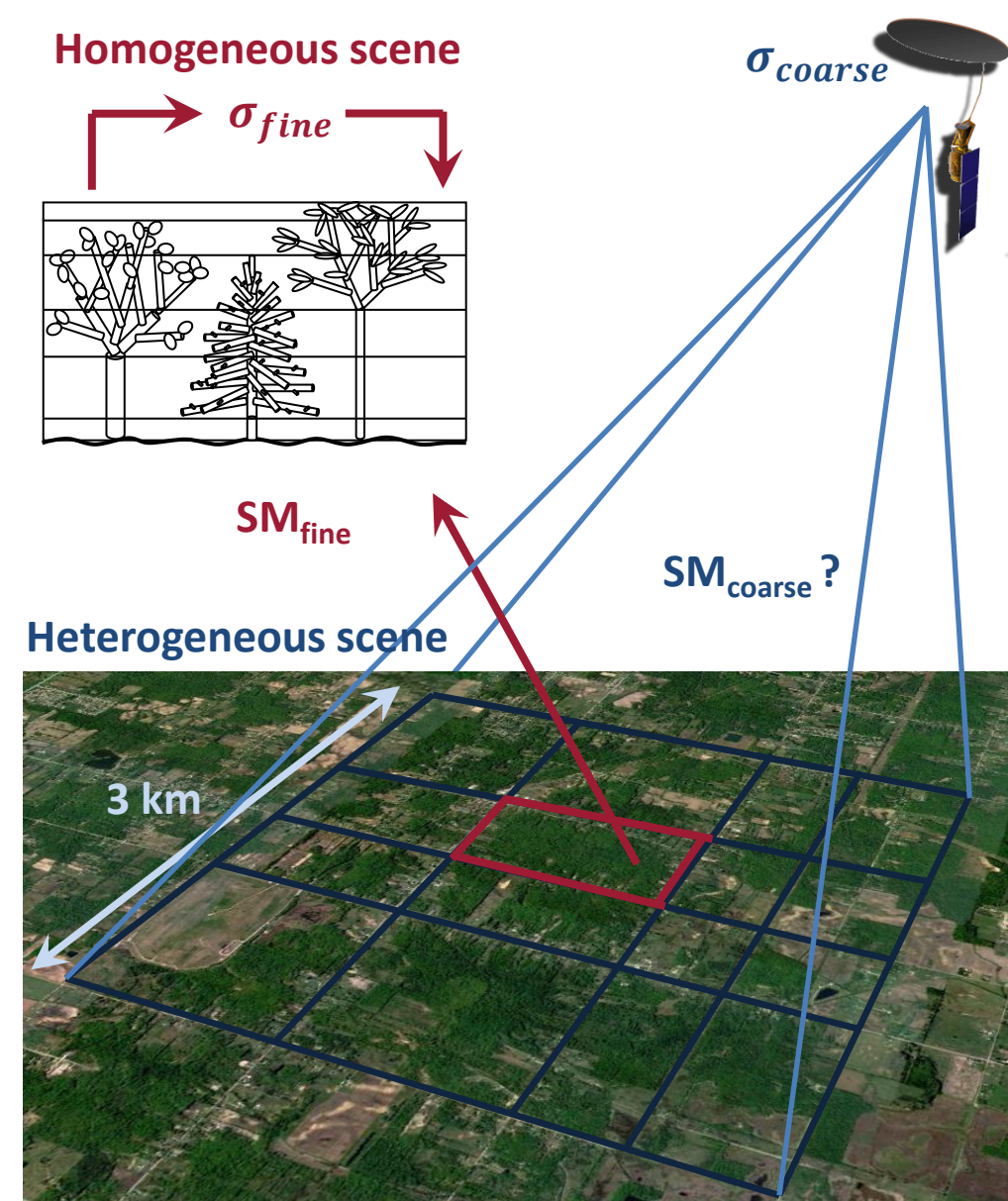
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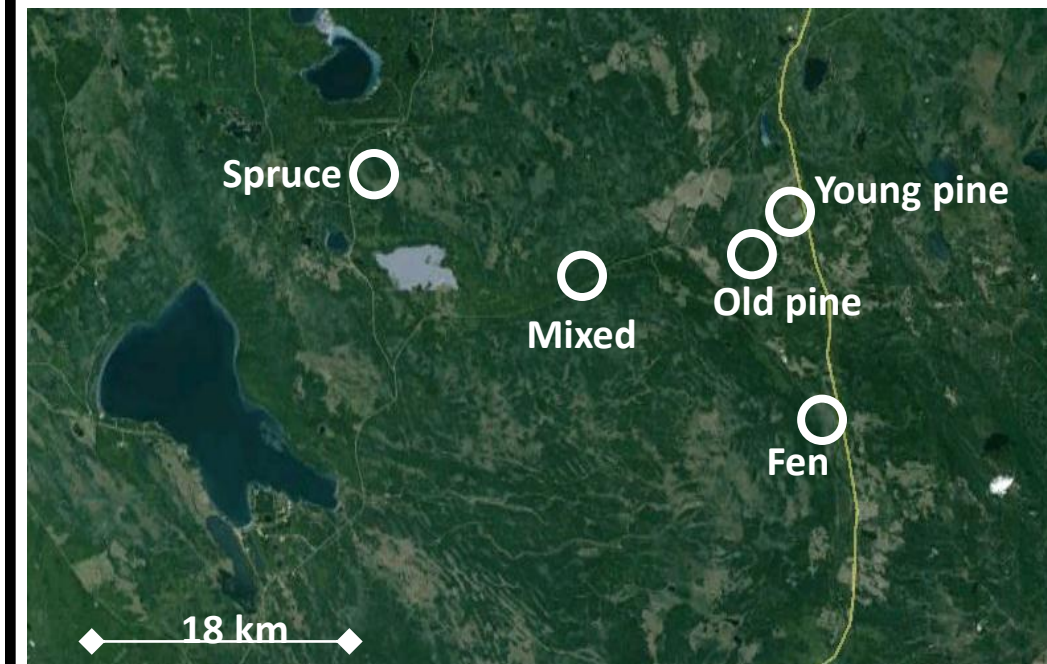
## Objectives

Soil Moisture Active Passive (SMAP) mission launching in October 2014 will carry an L-band radar delivering pixel size of 3 km x 3 km

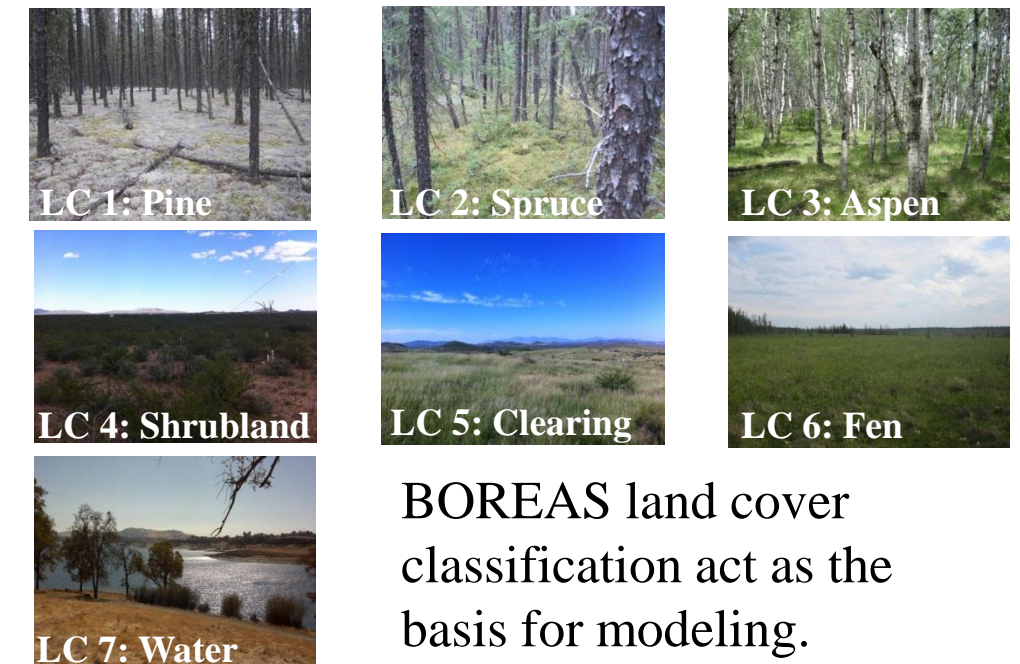
- ✓ Development of generalized forward model for a fine-scale homogeneous area
- ✓ Inversion for soil moisture over a fine-scale homogeneous area
- ❑ Radar measures one radar backscatter value over coarse-resolution image  
→ Coarse-scale soil moisture?



Sample site in Canada: BERMS / BOREAS



BOREAS land cover (LC) classification



BOREAS land cover classification act as the basis for modeling.

### Above-ground vegetation:

- Vegetation parameter obtained through field work

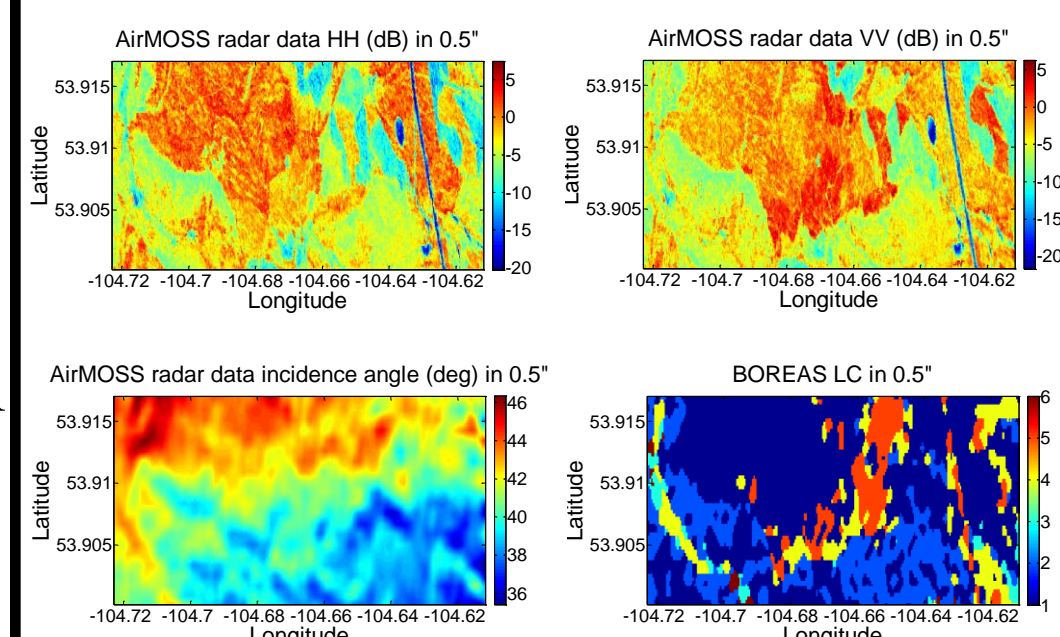
### Below-ground soil:

- Single soil layer with sandy soil

### Terrain topography

- Sample site is considered flat

Data layers over sample area



## Homogeneous ‘scaling’ functions

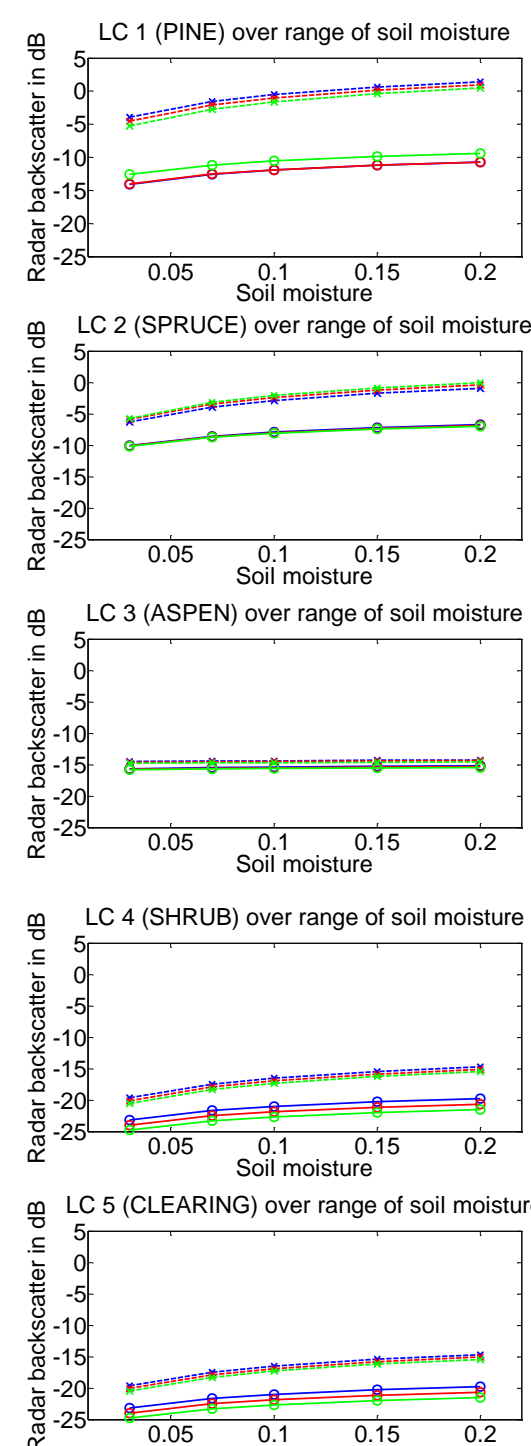
To restrict modeling space, discrete modeling points have been chosen:

- Land cover: 7 distinct types
- Soil moisture: 0.03, 0.07, 0.10, 0.15, 0.20 [m³/m³]
- Radar incidence angle: 38, 40, 42 [deg]

Homogenous ‘scaling’ functions show radar backscatter over soil moisture (figures to the right)

### General problem:

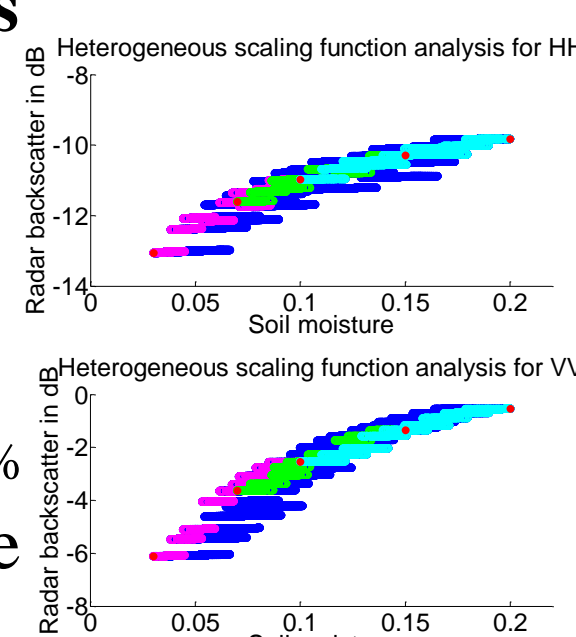
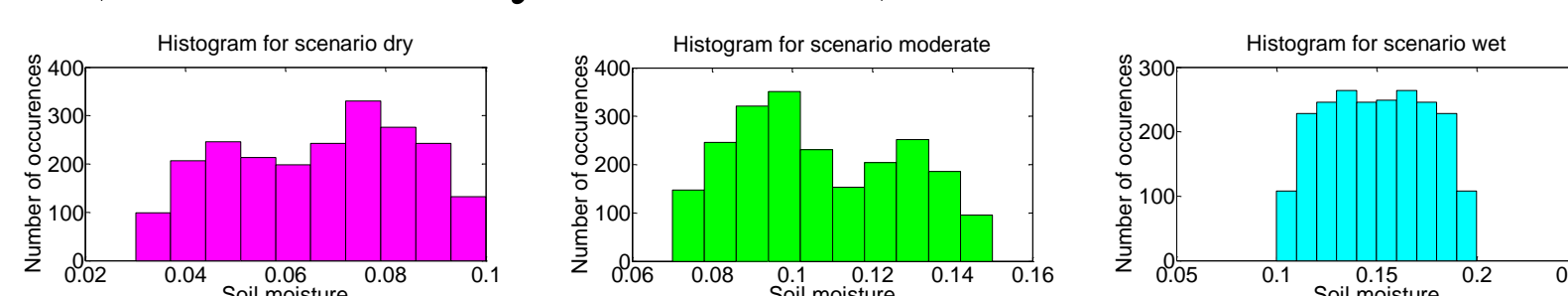
- Assume sample area represents coarse-scale image
- Measure total backscatter at coarse-scale resolution
- Want to find soil moisture at coarse-scale
- We know land cover distribution, soil texture and incidence angle
- We don’t know fine-scale measurements and fine-scale soil moisture



## Heterogeneous scaling function II

### Looking at all possible soil moisture combinations

- Total of 5<sup>7</sup> combinations of soil moistures
- Each measured coarse-scale radar backscatter value corresponds to range of potential coarse-scale soil moistures:
- Dry: 3%, 7%, 10%, Moderate: 7%, 10%, 15%, Wet: 10%, 15%, 20%
- Necessary to include statistics of the soil moisture distribution (not necessarily Gaussian !) via the weights



## Heterogeneous ‘scaling’ function

### Assuming all land cover types have equal soil moisture

- Total soil moisture is an average over all pixels within the coarse-scale image with N = total number of pixels:

$$SM_{coarse} = \frac{1}{N} \sum_i SM_i$$

- Total radar backscatter is the weighted average of the individual radar backscatter coefficients where M = number of LC types:

$$\sigma_{coarse} = \sum_i w_i \sigma_i$$

- Fine-level pixel radar backscatter is a function of soil moisture, vegetation and incidence angle:

$$\sigma_{fine} = f(SM_{fine}, veg_{fine}, inc_{fine})$$

- Using a nested technique, the total radar backscatter can be calculated as follows:

$$\sigma_{inc38} = w_{LC1} \sigma_{LC1 \& inc38} + \dots + w_{LC7} \sigma_{LC7 \& inc38}$$

$$\sigma_{inc40} = w_{LC1} \sigma_{LC1 \& inc40} + \dots + w_{LC7} \sigma_{LC7 \& inc40}$$

$$\sigma_{inc42} = w_{LC1} \sigma_{LC1 \& inc42} + \dots + w_{LC7} \sigma_{LC7 \& inc42}$$

where  $w_{LC1}$  to  $w_{LC7}$  are the respective percentage land cover for the coarse-scale image and  $\sigma_{LC1 \& inc38}$  to  $\sigma_{LC7 \& inc38}$  etc. are the homogeneous ‘scaling’ functions.

$$\sigma_{coarse} = w_{inc38} \sigma_{inc38} + w_{inc40} \sigma_{inc40} + w_{inc42} \sigma_{inc42}$$

where  $w_{inc38}$  to  $w_{inc42}$  are the percentage cover of incidence angle for the coarse-scale image.

This nested technique is separately applied to HH and VV:

